

BLDC Motor with Encoder · B1242N2B-

Applications: Precision control fields like medical instrument, industrial robot and so on. **Operating Environment:** $-15 \sim +45$

| Motor Characteristics | | | 150-14.0-EN520256-001 |
|--------------------------------|--------------------|------------------|-----------------------|
| Voltage | U | V | 14 |
| Terminal resistance | R | Ohm | 8.2 |
| No load speed | no | rpm | 15000 |
| No load current | I ₀ | mA | 100 |
| Rated torque | Т | mNm | 3.4 |
| Rated speed | n | rpm | 11000 |
| Rated current | | mA | 0.5 |
| Power | P _{max} . | W | 3.4 |
| Max. efficiency | η | % | 54 |
| Back-EMF constant | KE | mV/rpm | 0.88 |
| Torque constant | K _T | mNm/A | 8.4 |
| Rotor inertia | JRotor | gcm ² | 0.7 |
| Weight | | g | 19 |
| Length | L | mm | 42 |
| Encoder Characteristics | | | |
| Number of channels | | | 2 |
| Counts per turn | cpt | | 256 |
| Supply voltage | V | | 5 |
| Max operating frequency | kHz | | 110 |
| High level output voltage | V | | 2.4 Min |
| Low level output voltage | V | | 0.4 Max |
| Phase shift | °e | | 90 |
| Z index pulse width | °e | | _ |

Options:

Lead wires length, shaft length, special coils, gearheads, bearing type, encoder channels, encoder counts per turn

Dimension (mm) - B1242N2B-150-14.0-EN520256-001:

